

# Robot Manipulators and Automation

## AUTO4507

<b>Group Project</b>	<b>Drawing Robot Manipulator</b>	<b>weeks 6-12</b>
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**GROUPS:** Form groups of 2 students

**EQUIPMENT:** TTGO controller

Design and build a parallel pick and place robot that can hold a pen/pencil/marker and draw out shapes.



- Build the parallel arm robot from 3D-printed or laser-cut parts. Consider signing up for the Makers Club (requires inductions).
- Each of the 3 arms should be actuated by a motor, which is controlled by a TTGO ESP32 controller (provided).
- The robot needs to be able to draw at least a square, triangle and a circle.
- Write a program on the TTGO to display the key metrics of each arm.
- With forward-kinematics calculate and display the end effector position in x,y,z.
- Visualise the path plan of the robot on your laptop before running it.
- Your robot should be accessible via WIFI with a gui to select desired shape.

## BUDGET

The maximum budget for this project is \$50 per group. You will need to get a reimbursement through concur, details to be provided at a later date.

## DEMONSTRATION

During your lab session in week 12.

## VIDEO

Produce a video of about 1 min. length using time-lapse that shows the full construction of your robot and include your design choices.

## SUBMISSION

Submit one report per team as a softcopy plus hardcopy with official coversheet incl. declarations of all team members:

1. Project design report (*pdf*), which includes:
  - Report on which team member did what
  - CAD design
  - Software design
  - Diagrams, photos, screenshots, plots, etc.
  - Bill of Material with costing (budget)
  - User Manual

Include page numbers; max 10 pages plus 1 Title page

***Do NOT include:***

- o Program code
  - o Table of contents, etc.
2. Source code (*email to project supervisor only, no hardcopy*), clearly marking any imported code with referencing the source.

## MARKING

60% Functional Performance, Design, Complexity, Innovation  
30% Project Design Report  
10% Video